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on opposite sides of the longitudinal axis of the first arm, the supporting arm being arranged to exert a resilient force in the longitudinal direction of the cabling, and the supporting device comprising an auxiliary supporting arm with a second attachment arranged at the second arm.

B2

3. (Twice Amended) A manipulator according to claim 1, wherein the auxiliary arm is arranged at a turning disc of the manipulator.

B3

7. (Twice Amended) A method of holding and stretching cabling in a manipulator which comprises a plurality of mutually movable arms, a first of said arms being rotatably arranged around a first axis (A) and a second of said arms being rotatably arranged around a second axis (B), cabling extending along the arms which are mutually movable and a supporting device which supports a part of the cabling extending between the first arm and the second arm, the supporting device comprising a supporting arm which is rotatably arranged around a third axis (C) and is arranged at the first arm, and a first attachment, which surrounds the cabling, is arranged at the outer end of the supporting arm, the method comprising the steps of arranging the first attachment and the third axis on opposite sides of the longitudinal axis of the first arm, adapting the supporting arm to exert a spring force directed along the cabling, and providing the supporting device as an auxiliary arm with a second attachment which is arranged at the second arm.